

$\rightsquigarrow K_g$ is locally closed subset of the Hilbert scheme $\text{Hilb}(\mathbb{P}^r)$

smooth, irreducible open cond. $\mathcal{O}(1) \cong \omega_C^{\otimes k}$ closed condition $\{(Z \subseteq \mathbb{P}^r) \mid Z \text{ subscheme}\}$

$\rightsquigarrow K_g$ gets a scheme structure

How to recover M_g from K_g ? ($g \geq 2$) ^{$k \geq 5$}

$$\deg(\omega_C^{\otimes k}) = k(2g-2) = 2k(g-1) \geq 2g+1$$

$\hookrightarrow H^1(C, \omega_C^{\otimes k}) = 0$ (already seen)

$\hookrightarrow \omega_C^{\otimes k}$ very ample \rightsquigarrow complete lin. system defines an embedding into proj. space \mathbb{P}^r

$$h^0(C, \omega_C^{\otimes k}) = 2k(g-1) + 1 - g = r+1$$

Riemann-Roch + $h^1(\omega_C^{\otimes k}) = 0$

$\rightsquigarrow \forall C$ smooth curve $\exists \varphi: C \hookrightarrow \mathbb{P}^r$ non-deg. embedd. w/ $\varphi^*(\mathcal{O}(1)) = \omega_C^{\otimes k}$

Conversely such embeddings $\varphi \iff r+1$ sections in $H^0(C, \omega_C^{\otimes k}) \leftarrow \dim r+1$ non-degenerate \Rightarrow lin. indep.

specify a basis of $H^0(C, \omega_C^{\otimes k})$

$$K_g = \left\{ (C, [s_0 : \dots : s_r]) \mid \begin{array}{l} C \text{ smooth, gen } g \\ s_0, \dots, s_r \in H^0(C, \omega_C^{\otimes k}) \text{ basis} \end{array} \right\}$$

The group PGL_{r+1} acts on K_g by fixing C , acting on the set of basis elements, action is simply transitive on the set of such choices

\uparrow induced

$$\text{PGL}_{r+1} \curvearrowright \text{Hilb}(\mathbb{P}^r) \longleftarrow \text{PGL}_{r+1} \curvearrowright \mathbb{P}^r$$

$$\Rightarrow \text{Expect: } K_g / \text{PGL}_{r+1} \cong M_g = \{C\}$$

quotient(???)

Problem in general, it is not easy to define quotients in alg. geometry.

Solution Geometric invariant theory (GIT)

\hookrightarrow invented by Mumford

\hookrightarrow requires to check some conditions on K_g and action of PGL_{r+1} on it.

(points of K_g are semistable wrt the action of PGL_{r+1})

purely defined in terms of the group action.

What about stable curves?

C singular $\rightsquigarrow \Omega_C^1$ sheaf, not line bundle \rightsquigarrow no embed. $C \rightarrow \mathbb{P}^r$ w/ $\mathcal{O}(1)|_C = \Omega_C^1$
 \rightsquigarrow replace Ω_C^1 by dualizing sheaf ω_C

- \hookrightarrow exists for every proj. variety $X \rightarrow \omega_X$
- \hookrightarrow Serre duality

$$H^i(X, \mathcal{F}) \cong H^{dim X - i}(X, \mathcal{F}^\vee \otimes \omega_X)^\vee$$

$\hookrightarrow C$ nodal $\rightsquigarrow \omega_C$ line bundle

★ $\left(\begin{array}{l} C \text{ stable} \iff \omega_C \text{ ample} \\ \hookrightarrow \omega_C^{\otimes k} \text{ very ample for } k \geq 3 \end{array} \right.$

Define

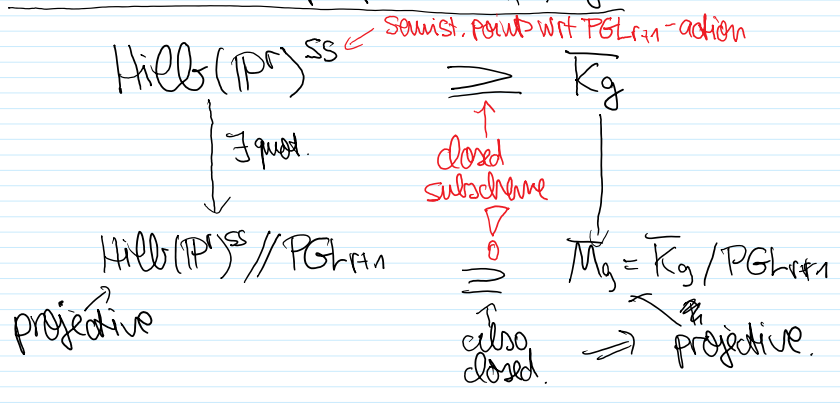
$$\overline{K}_g = \left\{ (C, \varphi: C \rightarrow \mathbb{P}^r) \mid \begin{array}{l} C \text{ stable curve of genus } g \\ \varphi \text{ non-deg. embedding} \\ \varphi^* \mathcal{O}(1) = \omega_C^{\otimes k} \end{array} \right\}$$

$\left(\begin{array}{l} \text{Fine moduli space} \\ C \cong \mathbb{P}^r \\ \text{has no automorphisms} \end{array} \right)$

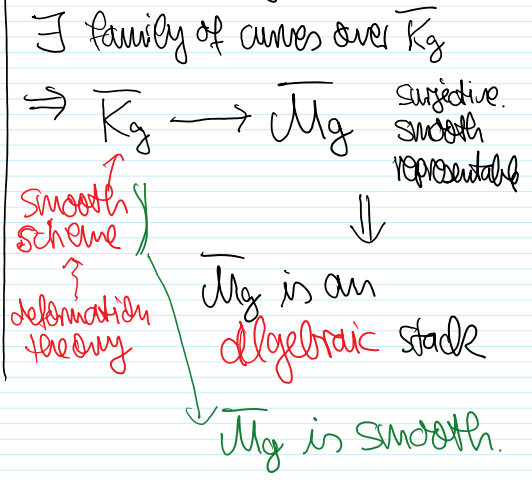
★ \rightsquigarrow every stable curve C appears in \overline{K}_g

\rightsquigarrow can repeat argument from before, get $\overline{M}_g = \overline{K}_g / \text{PGL}_{r+1}$.

Get some more properties of \overline{M}_g :



Also get something for the stacks \overline{M}_g :



Dimension and smoothness

Goal Why $\dim \mathcal{M}_g = 3g - 3 + n$?
 (also: why $\mathcal{M}_{g,n}$ smooth?)

Use Deformation theory / C

Given a scheme (or stack) \mathcal{M} , deformation theory studies morphisms $\text{Spec}(A) \rightarrow \mathcal{M}$ for A local Artinian \mathbb{C} -algebra.

A f.g. \mathbb{C} -algebra.
 A Artinian $\Leftrightarrow \dim_{\mathbb{C}} A < \infty$

Exa \mathbb{C} is trivial Artinian algebra.

$\mathbb{C}[X]/(\neq)$, $\neq \neq 0$ (\neq only one zero otherwise not local)

$A = \mathbb{C}[\epsilon]/(\epsilon^2)$ dual numbers

\mathcal{M} moduli space / stack
 $\leadsto \text{Spec}(A) \rightarrow \mathcal{M}$

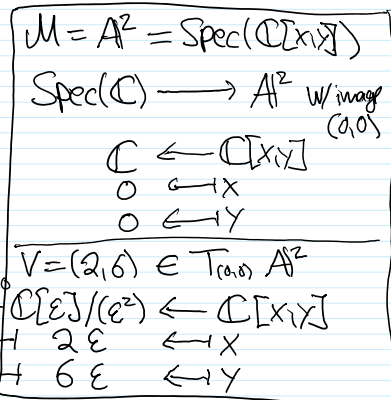
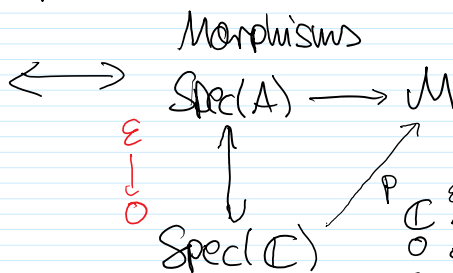
families over $\text{Spec}(A)$

Exercise \mathcal{M} complex scheme, $p: \text{Spec}(\mathbb{C}) \rightarrow \mathcal{M}$ a \mathbb{C} -point.

Show that there exists an equivalence:

$$v \in T_p \mathcal{M} = (\mathfrak{m}_{\mathcal{M},p} / \mathfrak{m}_{\mathcal{M},p}^2)^\vee$$

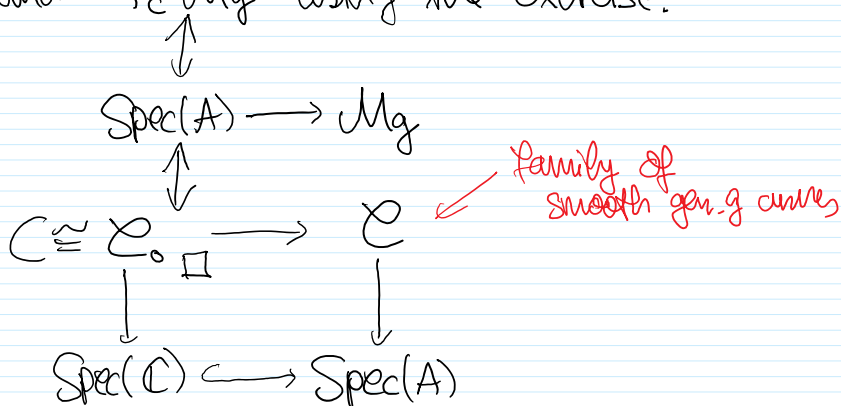
Zariski tangent space of \mathcal{M} at p



$$A = \mathbb{C}[\epsilon]/(\epsilon^2) \rightarrow \mathbb{C}$$

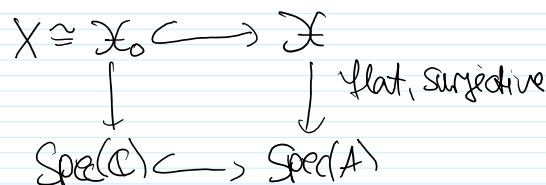
$$\epsilon \mapsto 0$$

So let's fix a smooth curve $C \in \mathcal{M}_g = \mathcal{M}$ and understand $T_C \mathcal{M}_g$ using the exercise.



Actually we can do story for more general varieties X :

Deformation of X over local Artinian ring A



$A = \mathbb{C}[\epsilon]/(\epsilon^2)$: first order deformation.

For X smooth we make the following observations:

a) $(\epsilon) \subset A$ unique prime ideal $\Rightarrow \text{Spec}(A) = \{pt\}$ as top. space

Similarly: $\mathcal{X}_0 \subseteq \mathcal{X}$ is cut out by square-zero ideal (ϵ)

Proposition \rightarrow isomorphism of top. spaces

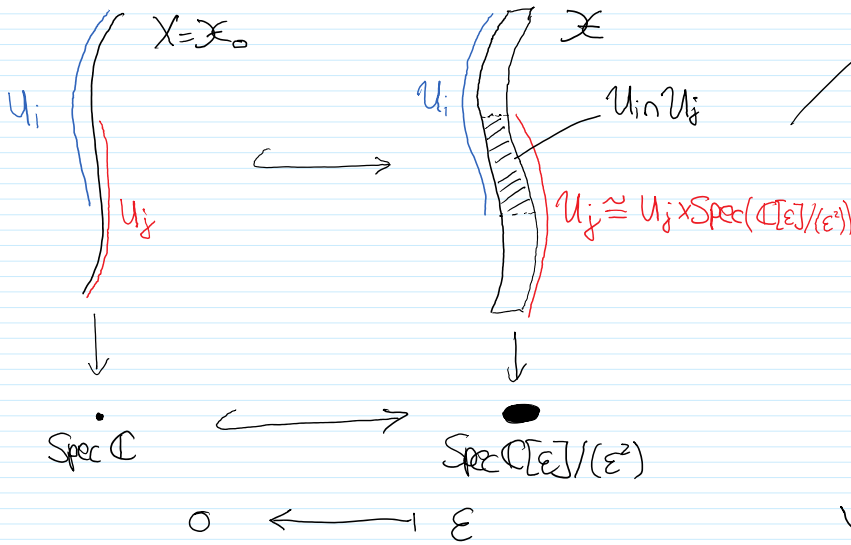
$U \subseteq \mathcal{X}_0 = X$ Zariski open $\xleftrightarrow{1:1}$ $U \subseteq \mathcal{X}$ Zar. open.

Prop. U affine $\iff U$ affine

b) Try to go to affine open covers U_i of $X \iff U_i$ of \mathcal{X} .

Fact All first-order deformations of smooth affine schemes U are trivial:

$$\begin{array}{ccc} U & \hookrightarrow & U \cong U \times \text{Spec}(A) \\ \downarrow & & \downarrow \\ \text{Spec}(\mathbb{C}) & \hookrightarrow & \text{Spec}(A) \end{array}$$



deformation is trivial on each of pieces U_i of affine cover

\Downarrow
all information is in gluing data on overlaps $U_i \cap U_j$

$$\psi_{ij}: U_{ij} \times \text{Spec}(A) \xrightarrow{\sim} U_{ij} \times \text{Spec}(A)$$

\square X separated $\rightsquigarrow U_{ij}$ also affine $\text{Spec}(B)$

Prop

Isomorphism $\psi_{ij}: U_{ij} \times \text{Spec}(A) \xrightarrow{\sim} \text{Spec}(B[\epsilon]/(\epsilon^2))$
restrict. to $\text{id}_{\text{Spec}(B)}$ over $\text{Spec}(\mathbb{C})$

$$B[\epsilon]/(\epsilon^2) \longrightarrow B[\epsilon]/(\epsilon^2)$$

\dots

$$B[\mathcal{E}]/(\mathcal{E}) \longrightarrow B[\mathcal{E}]/(\mathcal{E}^2)$$

$$X + \mathcal{E} \cdot Y \longmapsto X + \mathcal{E}(Y + \eta_{ij}(x))$$

$$\eta_{ij} \in \text{Der}_{\mathbb{C}}(B, B)$$

$$\uparrow$$

$$V_{ij} \in H^0(U_{ij}, T_{U_{ij}})$$

\mathbb{C} -linear derivations.

Next time

$$(V_{ij})_{ij} \in \check{H}^1(X, T_X) \longleftrightarrow$$

data of deformation

Exercise ($C=X$)

$$T_{\mathbb{C}} \mathcal{M}_g$$

$$\Rightarrow T_{\mathbb{C}} \mathcal{M}_g = H^1(C, T_C)$$

Exercise $\dim H^1(C, T_C) = 3g - 3$